

# Polarimetry with Phased-Array Feeds

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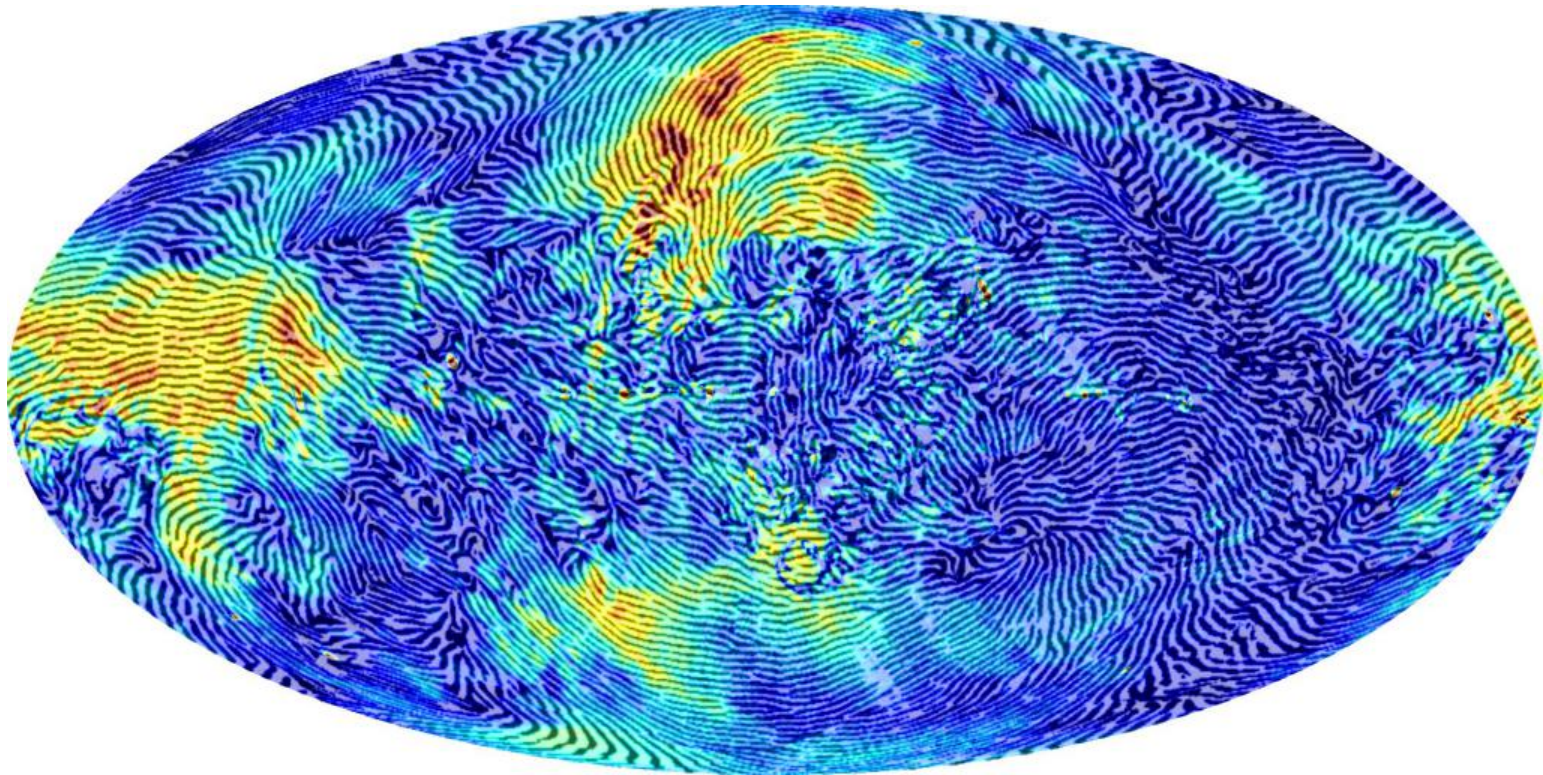
# Outline

- Radio astronomy & polarimetry
- Stokes parameters
- PHAD receiving system
- Calibration, measurements & results



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# All-Sky Polarization Map



*Courtesy Maik Wolleben and Tom Landecker*



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# SKA Design Reference Mission

[http://www.skatelescope.org/PDF/091001\\_DRM\\_v0.4.pdf](http://www.skatelescope.org/PDF/091001_DRM_v0.4.pdf)

- Cosmic Magnetism Deep Field
- Wide-Field Polarimetry
- Testing Theories of Gravity using Ultra-relativistic Binaries
- Pulsar Timing to Detect Gravitational Waves



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## Summary of Requirements

- frequency range:  $\sim 0.3 - 3$  GHz
- bandwidth: 0.5 GHz
- polarization purity
  - polarization surveys: 25 dB (wide field)
  - pulsar timing: 40 dB (boresight, narrow field)
- time resolution: 50  $\mu$ s (100 ns for timing)
- survey time
  - deep field: 100 – 400 hours per pointing
  - wide field: 1 hour/field



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# Polarization — Two Worldviews

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Engineers	Astronomers
highly-polarized sources	weakly-polarized sources $\lesssim 10\%$
bright sources	weak sources ( $\sim 10$ Jy)
co-pol/cross-pol/ellipticity	Stokes (un-pol/linear/circular)

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## Typical Calibration Sources

Source	$S$ , Jy/pol	% pol	$P_s$ , Jy
Cas A	1861	0.27	10
Cyg A	1589	0.5	17
3C270	17.2	7.6	2.6
3C286	14.8	9.5	2.7

(1.4 GHz)

Also regions of extended emission visible in N sky

- Question: what level of polarization purity is possible when polarized signal of calibrator is swamped by unpolarized emission?



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# Stokes Parameters

- Stokes Parameters are a way of describing a partially-polarized radiation field

$$I = \langle |e_x|^2 + |e_y|^2 \rangle$$

$$Q = \langle |e_x|^2 - |e_y|^2 \rangle$$

$$U = 2 \Re \langle e_x \cdot e_y^* \rangle$$

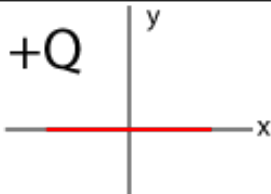
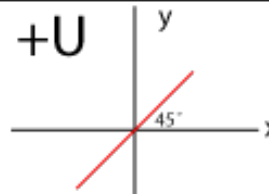
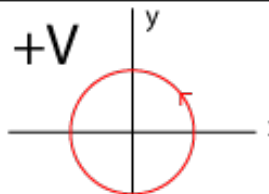
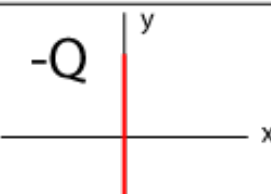
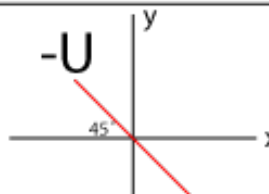
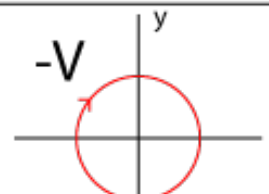
$$V = 2 \Im \langle e_x \cdot e_y^* \rangle$$

$$I^2 \geq Q^2 + U^2 + V^2$$





# Stokes Parameters (Pictorially)

100% Q	100% U	100% V
<p><b>+Q</b></p>  <p><math>Q &gt; 0; U = 0; V = 0</math> (a)</p>	<p><b>+U</b></p>  <p><math>Q = 0; U &gt; 0; V = 0</math> (c)</p>	<p><b>+V</b></p>  <p><math>Q = 0; U = 0; V &gt; 0</math> (e)</p>
<p><b>-Q</b></p>  <p><math>Q &lt; 0; U = 0; V = 0</math> (b)</p>	<p><b>-U</b></p>  <p><math>Q = 0; U &lt; 0; V = 0</math> (d)</p>	<p><b>-V</b></p>  <p><math>Q = 0; U = 0; V &lt; 0</math> (f)</p>

[http://en.wikipedia.org/wiki/Stokes\\_parameters](http://en.wikipedia.org/wiki/Stokes_parameters)



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## References

- Heiles' tutorial (single dish mostly)
  - *Single-Dish Radio Astronomy: Techniques and Applications*, ASP vol. 278, 2002
  - this reference and other useful memos at [http://astro.berkeley.edu/~heiles/handouts/handouts\\_radio.html](http://astro.berkeley.edu/~heiles/handouts/handouts_radio.html)
- Hamaker/Sault/Bregman series of papers on polarimetry in *Astronomy and Astrophysics Supplements* (interferometry mostly)
  - search ADS
  - Johan Hamaker's web page: <http://www.astron.nl/~hamaker/>



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## PHAD receiving system

- Phased-Array Feed Demonstrator = PHAD
- *Engineering* demonstrator
- Vivaldi-element based array (dual polarization)
- 84 active elements ( $6 \times 7 = 42$  per polarization)
- Data store  $\rightarrow$  off-line beamforming



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## PHAD Specifications

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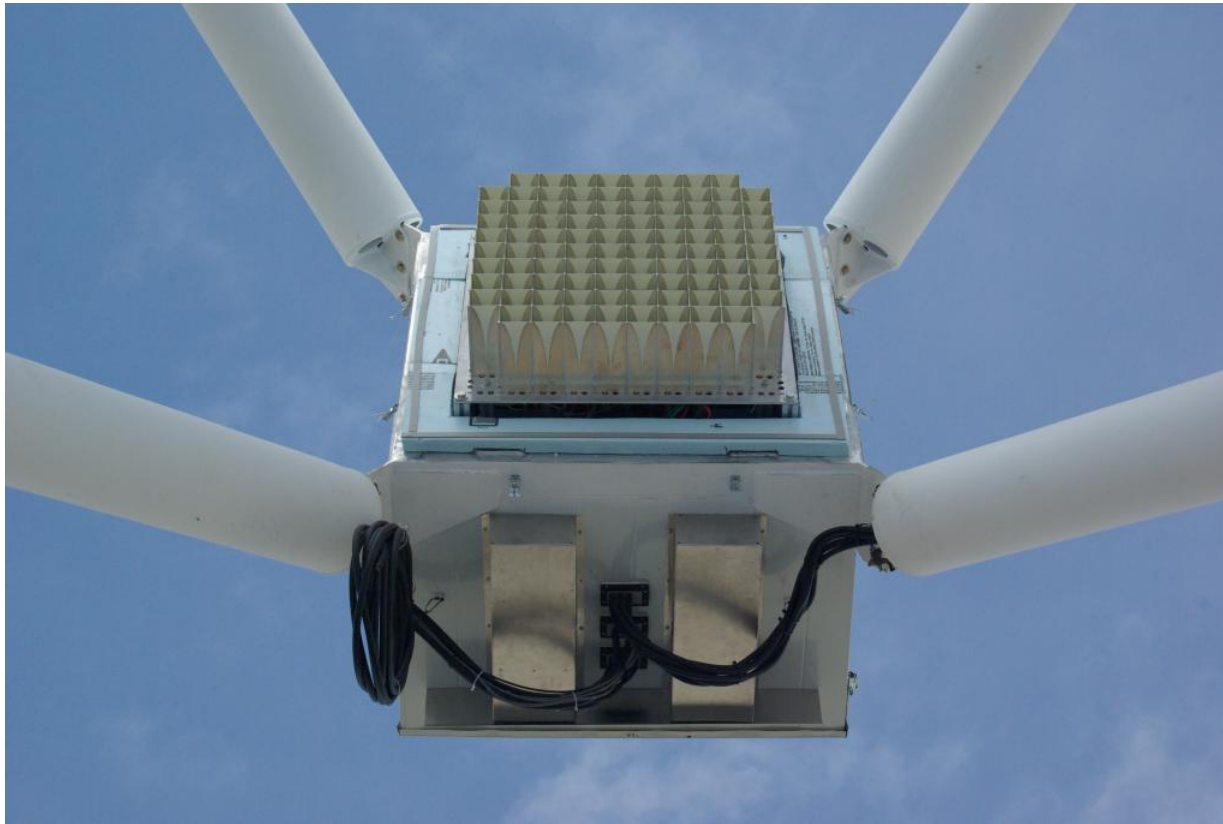
Frequency range	1–2 GHz
Array size	0.76 m × 0.76 m
Number of elements	9 × 10 × 2 polarizations = 180
Active elements	42 × 2 polarizations = 84
Element spacing	$\lambda_{min}/2 = 76$ mm
Receiver architecture	direct conversion (complex)
Bandwidth	4 MHz/sideband
Sample rate	10 MHz
Sample precision	14 bits
Memory depth	16 MB/element

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# PHAD Array



# PHAD on CART Dish

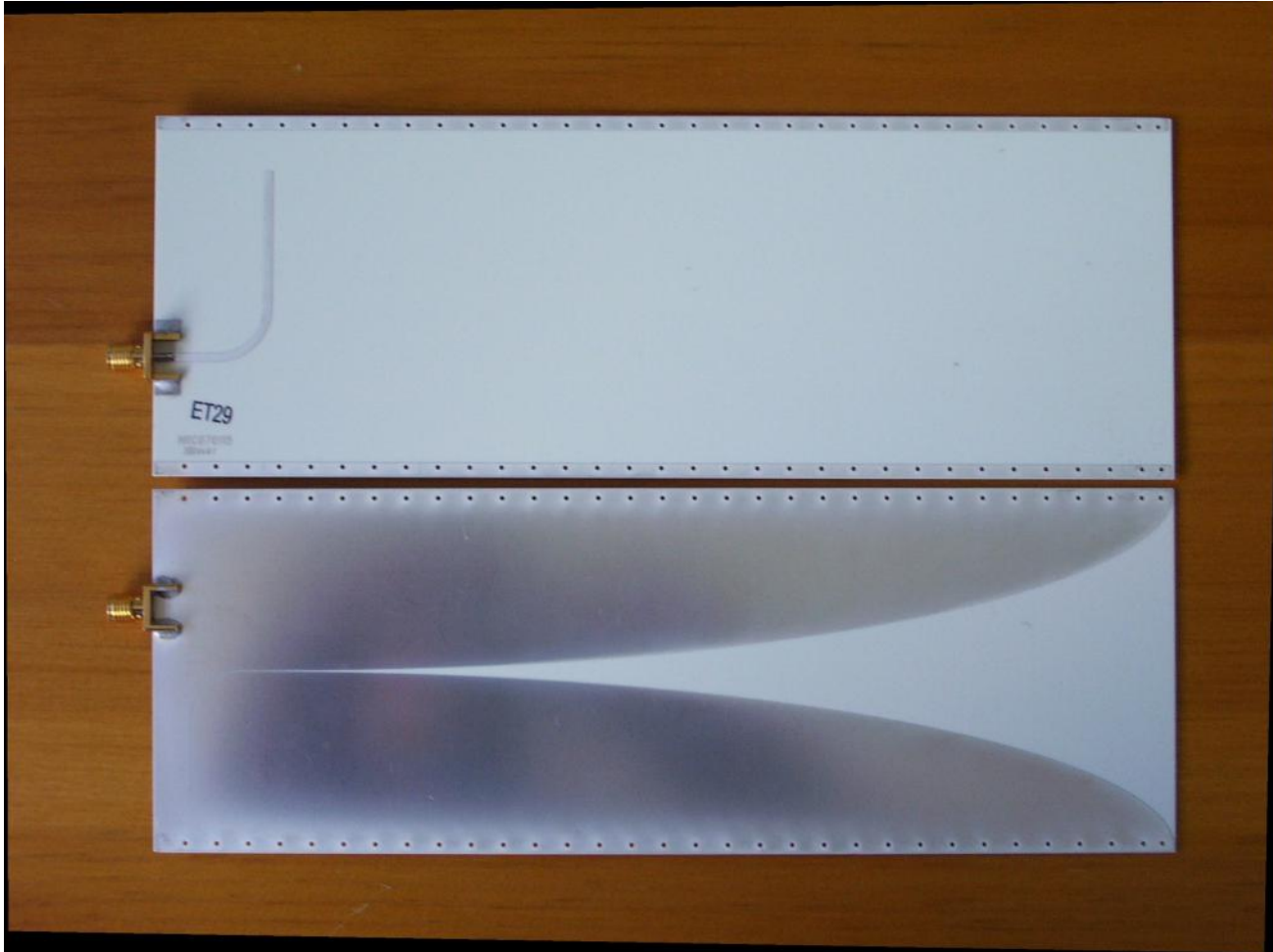


- 10-metre diameter
- $f/D = 0.45 \Rightarrow \theta_{half} = 58^\circ$
- RMS surface error 1.2 mm
- composite construction

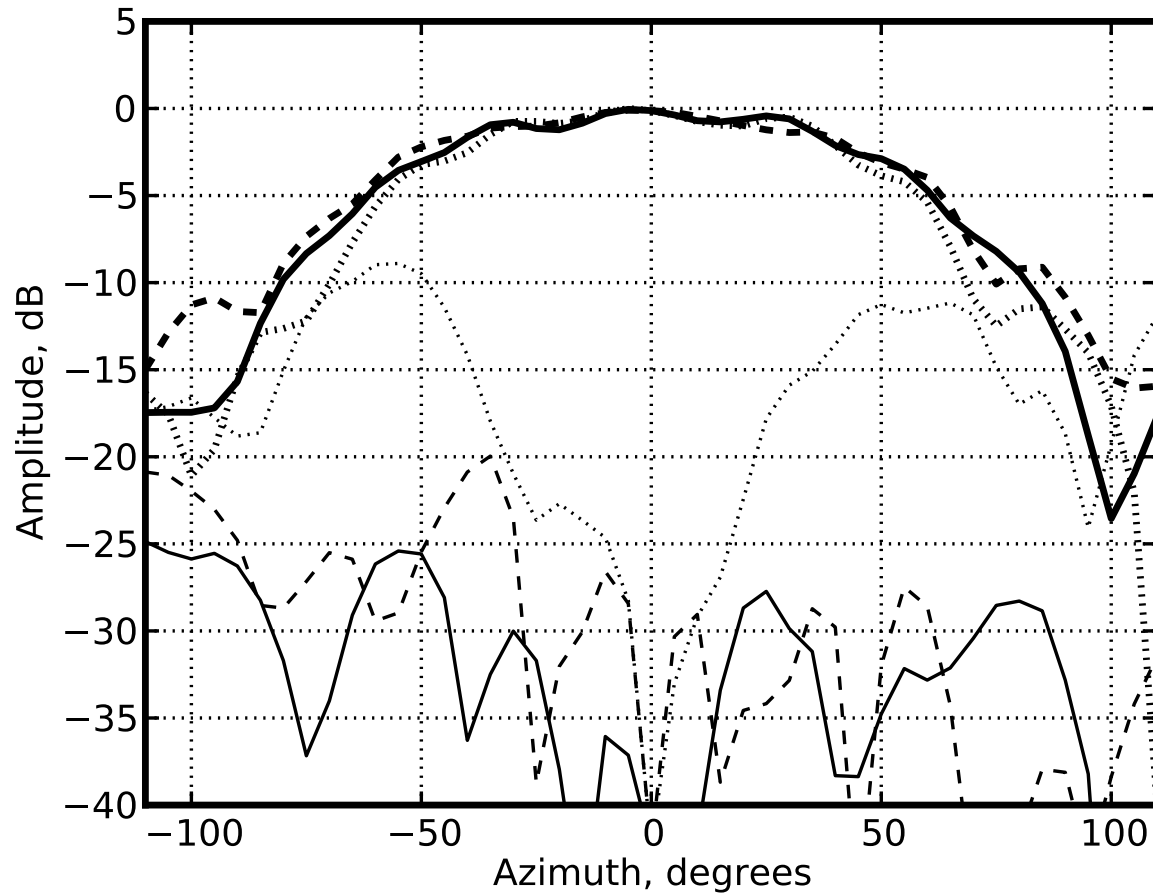


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# Vivaldi Element Layout

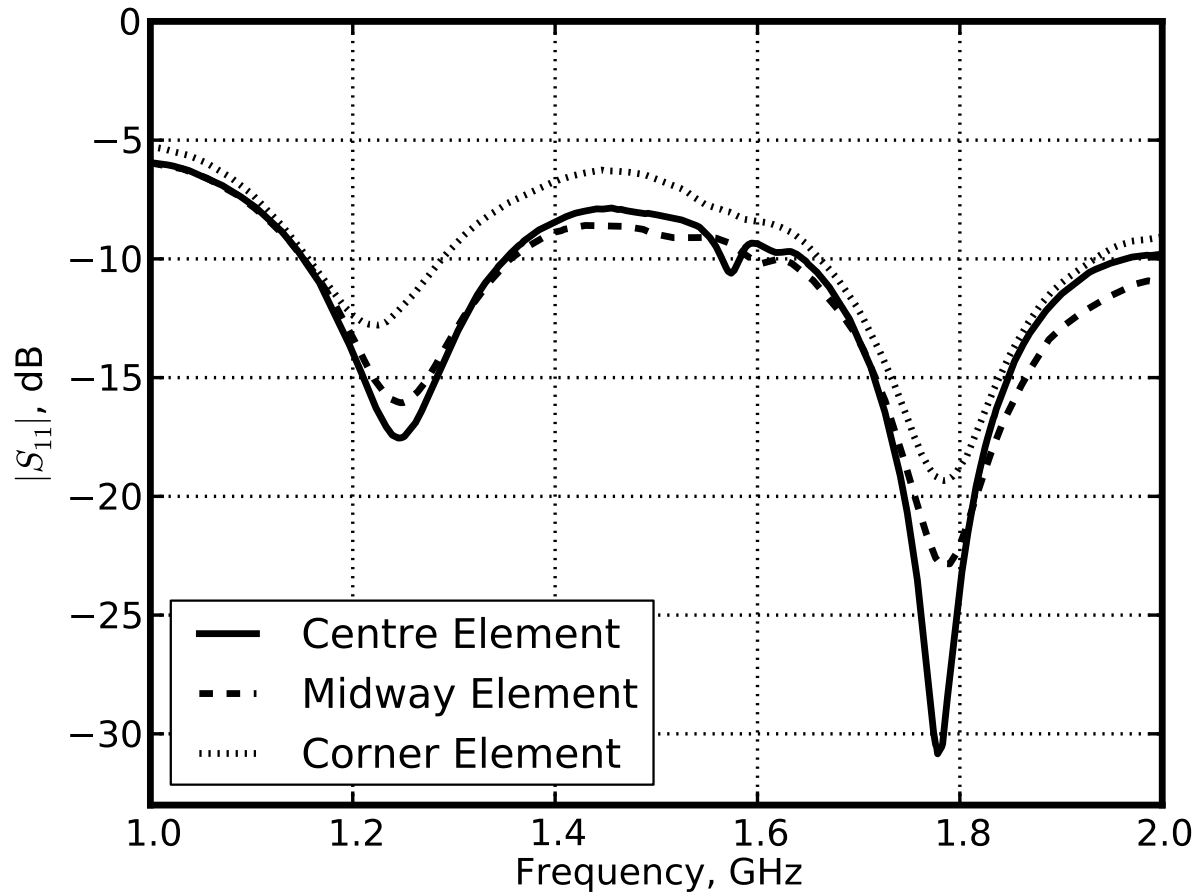


# Typical Element Patterns





## Typical Element $S_{11}$ (Passive)



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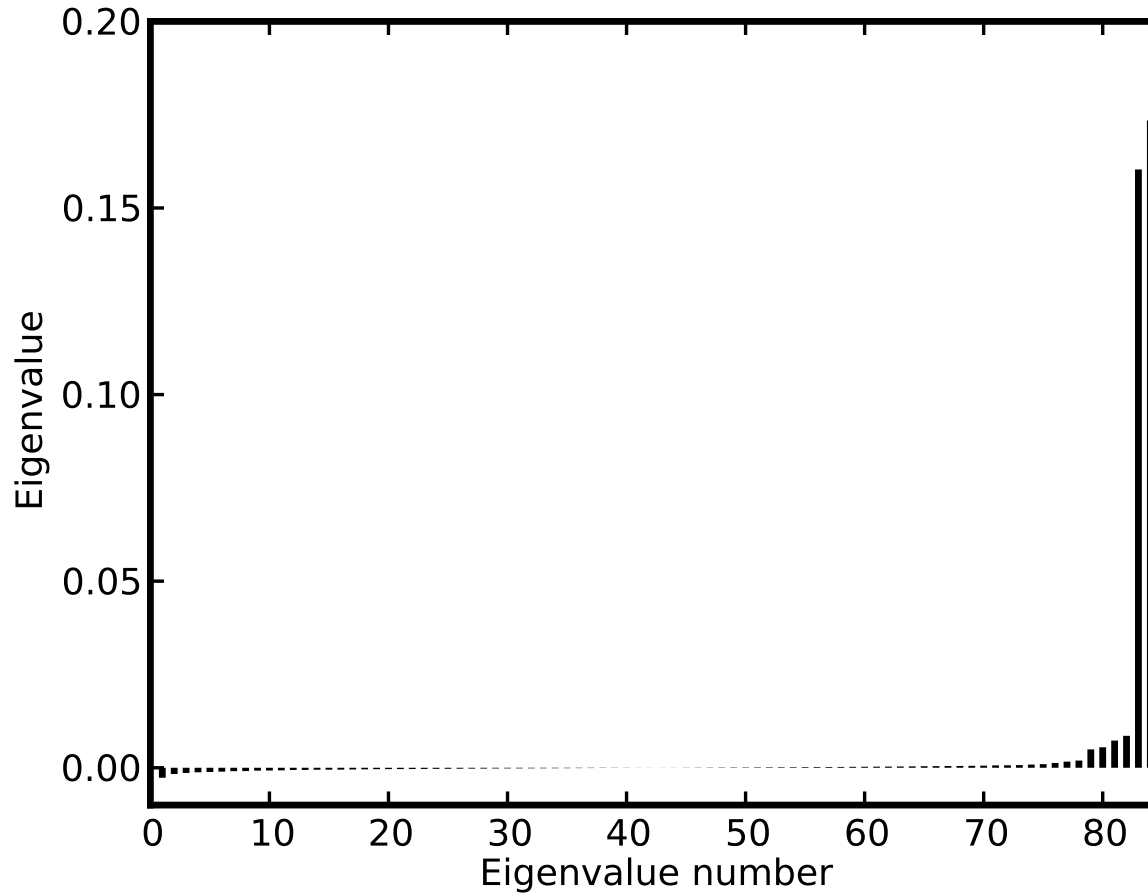
# Beamformer Calibration

Use Conjugate Field Matching (CFM) for two polarizations

1. Observe unpolarized calibration source and calculate covariance  
 $\Rightarrow \mathbf{R}_{on}$
2. Observe dark sky and calculate covariance  $\Rightarrow \mathbf{R}_{off}$
3. Calculate difference  $\mathbf{R}_{on} - \mathbf{R}_{off}$  and calculate eigenvectors
4. Select two dominant eigenvectors
5. Conjugate of eigenvectors are weights for the two polarizations

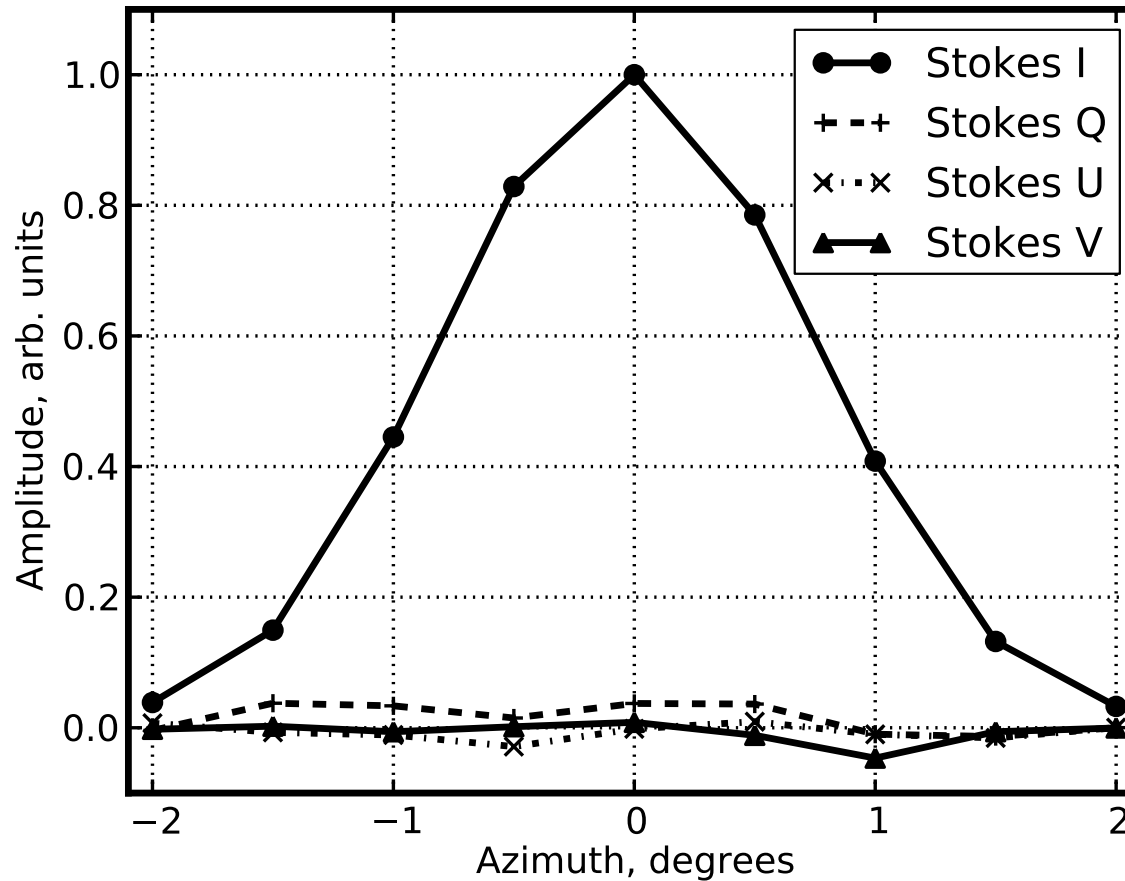


# Eigenvalue Spectrum



# Synthesized Stokes Beams

## PHAD Polarization Response



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## Summary of Instrumental Polarization

parameter		with cross-pol		no cross-pol	
$Q/I$	$\leftrightarrow$	0.062	-12 dB	0.055	-13 dB
$U/I$	$\nearrow$	0.006	-22 dB	0.027	-16 dB
$V/I$	$\circlearrowright$	0.007	-22 dB	0.021	-17 dB

$$\frac{I_{x-pol}}{I_{no-x-pol}} = 1.04 \text{ (0.17 dB)}$$



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## Is This Calibration Complete?

- We have two orthogonal beams
- We have not established polarization angle
  - CFM solutions for different beams will have different rotational angles
  - observe astronomical calibrator with known polarization angle
  - or on-dish calibration source (watch out for reflections)
  - or cross-correlation with reference antenna in an interferometer
- Do not have “handedness” of  $U$  and  $V$  (phase between  $e_x$  and  $e_y$ )
  - requires another observation with a polarized source
- *But*, at this point calibration is similar to what is done for conventional horn feeds



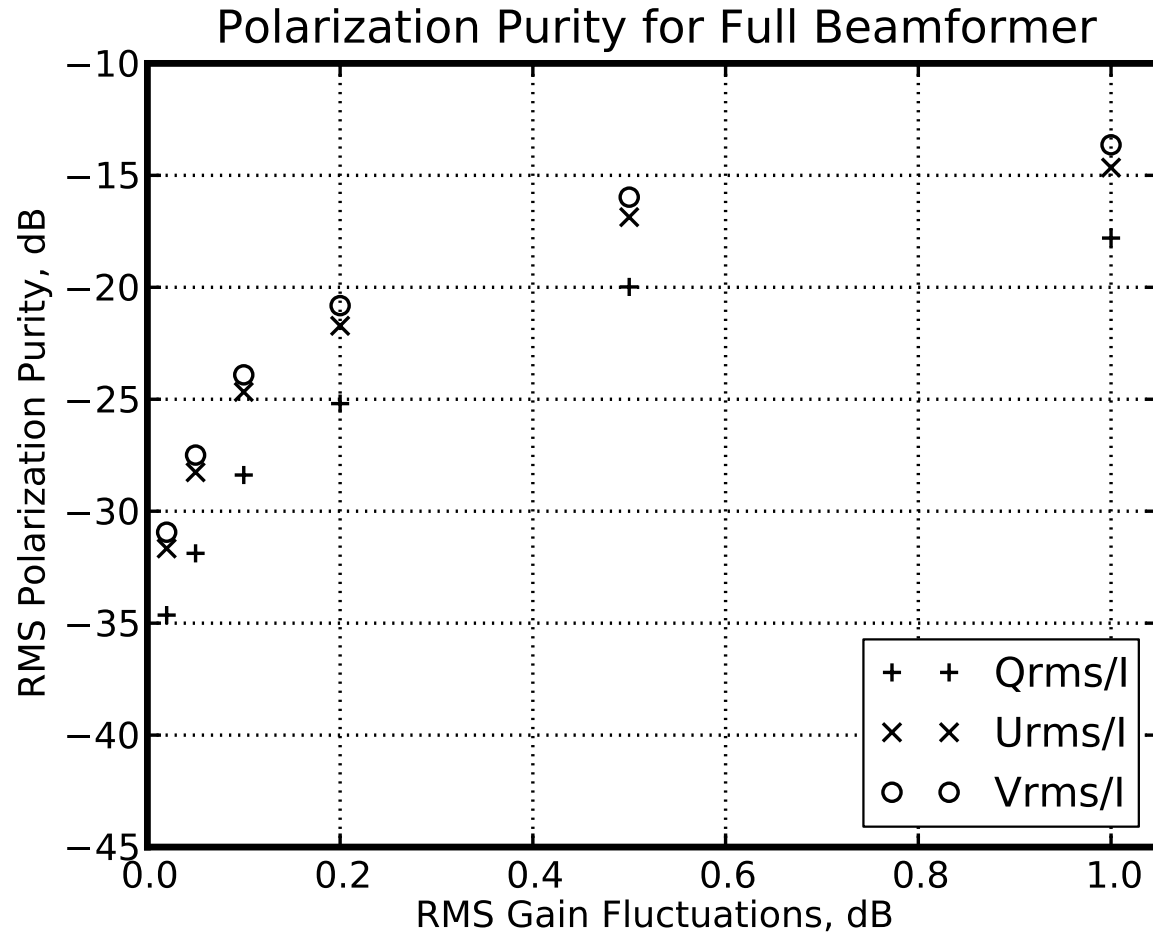
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# Electronic Gain Stability

- As long as Stokes beams are stable, instrumental polarization can be corrected
- How stable?
- Simulate by introducing random gain errors into recorded data streams and reprocessing
- Compare with a simple model:  $e = \sum_{i=1}^n (1 + \Delta g \rho(i))$

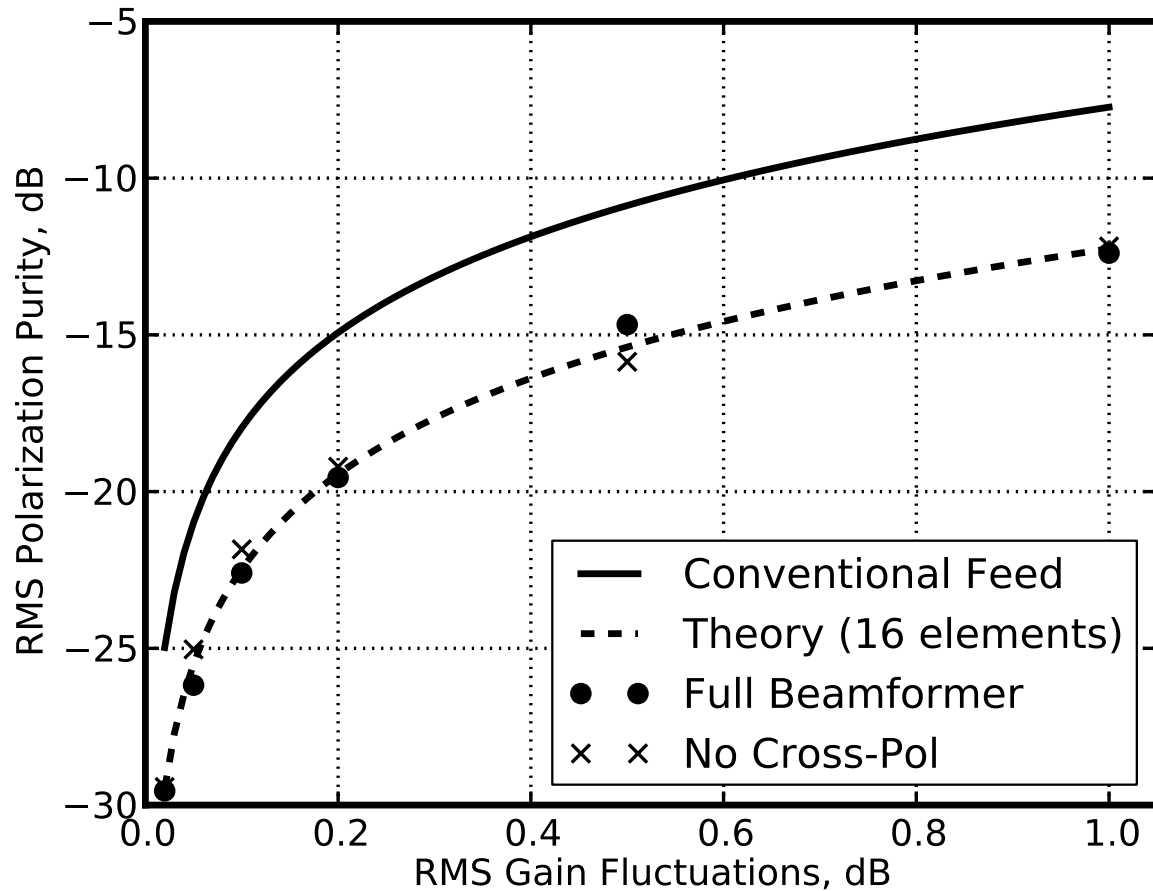


# Polarization Purity with Gain Fluctuations

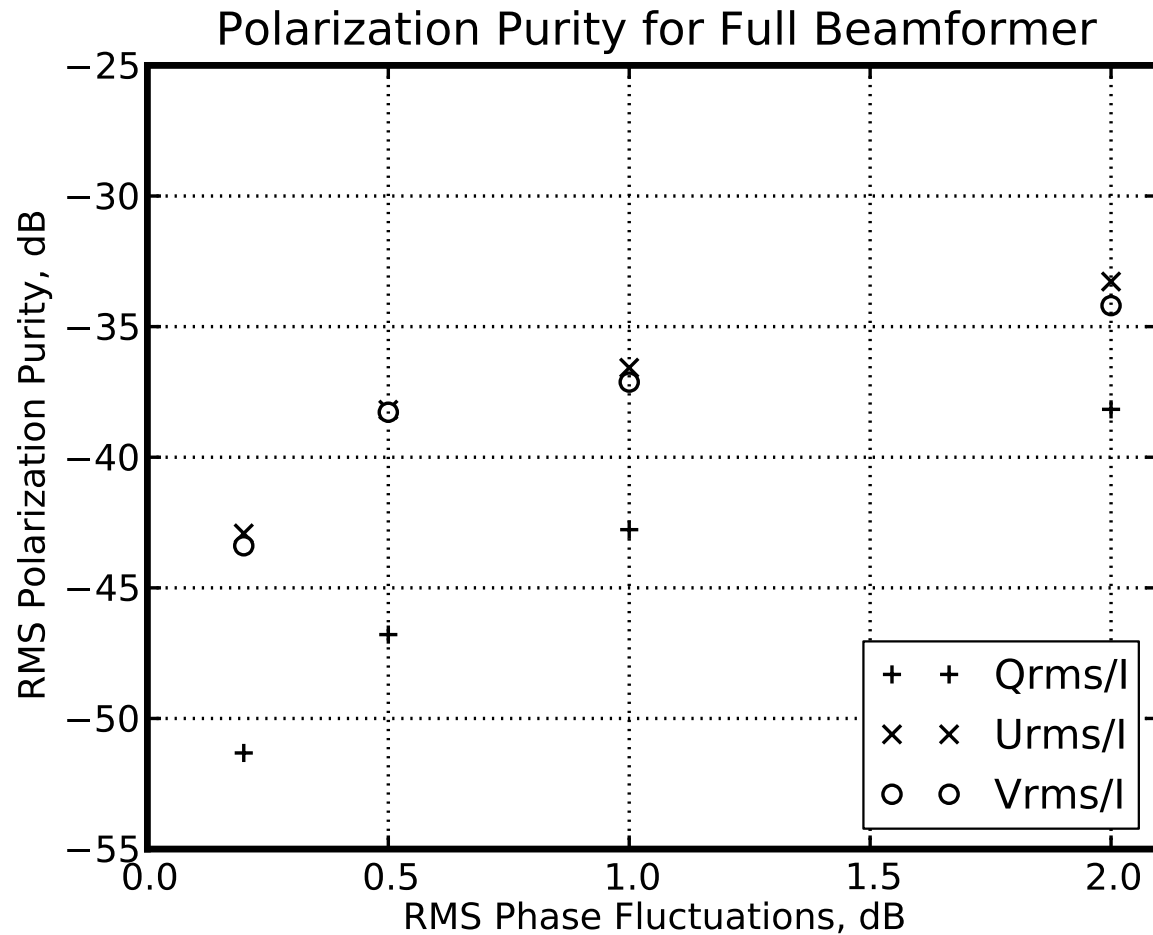




# Polarization Purity with Gain Fluctuations (II)



# Polarization Purity with Phase Fluctuations



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## Discussion on Stability Specification

- Gain stability more stringent than phase stability
  - to meet 40 dB spec need gain stability of 0.0018 dB
  - ATA measures 0.0009 dB over 1–3 minutes (Memo 76)
  - phase stability of  $\sim 0.2^\circ$
- Cross-coupling between Stokes parameters for PAFs more complicated than horn feeds
  - gain fluctuations *are* seen in  $U$  and  $V$
  - stability will be an issue with wide-band single-pixel feeds too



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# Discussion on Calibration System

- Calibration system crucial for PAFs
  - {monitor/correct} {gain/phase} fluctuations in receivers
  - provide coordinate system references
  - dish with very good polarization properties to act as a polarization reference in an interferometer?
- Sidelobes are highly polarized so spillover can introduce a contaminating signal



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# Acknowledgments

## **PHAD Team:**

Tom Burgess, Rob Messing, Rick Smegal, Gary Hovey, Peter Dewdney

## **Useful discussions on polarimetry:**

Maik Wolleben, Tom Landecker, Tony Willis, Karl Warnick



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# The End

